

Restricted Constraints in the Problem of Maximum Attainable Flow in Minimum Cost in a Network

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Abstract

In this paper we have considered a version of restricted constraints in the problem of maximum attainable flow (capacity) in minimum cost (distance) in a network (Ahmed, Das, & Purusotham, 2012b). By restricted constraints one means that the link(s) (cities or stations or nodes) are completed (or visited) in such a way that a particular link is to be preceded (completed or visited) by another link (precedence relation need not be immediate).

Here the aim is to obtain an optimal route of a more realistic situation as to scheduling a restricted constraints to a maximum flows at a minimum cost from a source to a destination. The distance (cost) and arc capacity between any two stations are given.

Keywords: Distance and Capacity Matrix, Lexicographic Search Approach, Restricted Constraints and Algorithm

Introduction

A network consists of a set of nodes (vertices) and a set of arcs (edges). Each node represents a location (city) and each arc represents the connection (road link) between two different locations (cities). The number(s) on each arc represents the distance (cost, time) between the two locations (cities), capacity of the link between the cities, etc.

Let us consider the situation of a pipe network used to transfer fluid (oil, water, etc.) from one location to another. The maximum flow of fluid in each pipe- segment will be

limited because of a particular value (capacity of the arc) depending on the diameter of the pipe in that segment or the slope of the pipe in the segment. The arc $i - j$ i.e. pipe segment between any two locations i and j of the network is associated with the following data:

- (i) Maximum permitted flow of fluid per unit time from node i to the node j and / or
- (ii) Maximum permitted flow of fluid per unit time from node j to the node i .

The importance of restricted constraints like precedence constraints, fixed position constraints and mixed constraints etc. in a routing problem has been very well discussed by Scroggs and Tharp (1972). It occurs frequently in many realistic situations. For example, a salesman has a quota of products to sell on a tour and he may want to visit the better prospects early. An early supply to a station may be made to the flood prone areas than the other stations to avoid the difficult situation it might fall in; a CEO of a company may plan a tour and need to be in a certain station on a particular date, etc.

Here, we have considered precedence constraints in the problem of maximum attainable flow in minimum cost in a network. By precedence constraints one means that the stations (cities or nodes) are visited in such a way that a particular station is to be preceded by another specific station. Precedence relation need not be immediate. Let us assume restricted relations are of the type $(a < b)$ or $(a < b < c)$ or $(a, b, c < d)$ etc. and these lead to $(b \blacklozenge a = \times)$, $(c \blacklozenge b \blacklozenge a = \times)$, $(d \blacklozenge a, b, c = \times)$, etc.

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Brief Review of Literature

Routing problems pertain to the search for a shortest route (minimum cost or minimum distance) or maximum flow, etc. connecting two specified stations or nodes described as ‘source’ and ‘sink’. The problem of determining the shortest route under some constraints has been solved (Bansal & Kumar, 1970; Pandit, 1962, 1963).

In all these problems it has been assumed that the link capacities are infinite. Ford and Fulkerson (1956, 1962) introduced the idea of imposing capacity restriction on the links. Some references along this line can be made as Fathabadi and Shirdel (2002), Sedeno-Noda and Gonzalez-Martin (2003). Purusotham and Sundara Murthy (2011, 2012) proposed a Pandit’s Maxi-Min algorithm for solving the maximum flow with minimum cost problem and showed the efficiency of the algorithm in their paper.

Many solution algorithms have been appeared for the problem(s) to find a maximum capacity route (Das, 1976) or maximum capacity flow using as many routes as possible (Das & Ahmed, 2001; Fulkerson, 1961). Many situations have appeared to the search for a shortest route connecting two specified situations or nodes (Bellman, 1958; Dantzig, 1957c; Peart, 1960; Pollack & Walter, 1960; Purusotham & Sundara, 2011). Saksena and Kumar (1966) have solved a variant of this problem when the route must pass through some specified nodes. Other flow problems are of the type to find the minimal cost flow where each arc is assigned with (cost, capacity) values (Klein, 1967).

We solved the problem by applying lexicographic search method to search for the optimal route(s) giving the maximum possible flow of the network with minimum cost.

Notation and Statement of the Problem

The problem we have considered here is as given below.

Let the undirected network consist of nodes which for convenience are denoted in any order of sequence $S, 1, 2, \dots, (D-1), D$. It is assumed that certain capacity restriction and unit-shipping cost is associated with each link of the network. The problem is to schedule maximum flow in minimum possible cost from some specified node,

say source denoted by S , to another specified node, say destination denoted by D , using the restricted constraints, i.e., the stations are visited in such a way that a particular station is preceded by another given station(s).

Let us assume that the precedence relations are of type, $a < b, c < e, b < d, e < f, g < h$ etc.

The precedence relation being transitive, we can form precedence chains from the above relations as, $(S < a < b < d < D), (S < c < e < f < D), (S < g < h < D)$ and $(S < a < b < d < D)$; implies, $(S \blacklozenge b = \times), (S \blacklozenge d = \times), (b \blacklozenge a = \times), (d \blacklozenge b = \times), (d \blacklozenge a = \times), (a \blacklozenge D = \times)$ and $(b \blacklozenge D = \times)$.

It is, of course, not necessary that the nodes $(a, b, d), (c, e, f)$ etc. are to be visited in a string, i.e., ‘ a ’ need not be immediately followed by ‘ b ’, ‘ d ’ or ‘ c ’ need not be immediately followed by ‘ e ’, ‘ f ’ etc. However, when $(a, b, d), (c, e, f)$ or (g, p) are in a string, a merger of nodes into one and deletion of appropriate rows and columns in the distance (cost) matrix reduces it to a problem virtually without constraints.

Similarly, for other relations, the cost matrix can be suitably modified.

In particular, in the present study, we consider the precedence relations as $(2, 5 < 7 < 9)$ and $(1 < 3 < 5, 8)$. From these relations we construct a table of predecessors for the different nodes as shown in Table 1. However, in the table, we have only entered the predecessors which are directly prescribed by the restrictions. We shall denote the set of predecessor of a node ‘ a ’ by $P(a)$.

Table 1: List of Predecessors for the Different Nodes

Nodes	$P(a)$ (other than the depot)
S	---
1	---
2	---
3	1
4	---
5	1, 3
6	---
7	2, 5
8	1, 3
9	2, 5, 7

Mathematical Formulation

Suppose, we have a network with vertices $V=\{1, 2, \dots, n\}$, undirected edges $E=\{(i,j) \in V \times V\}$, a non-negative integral valued function ‘ k ’ giving the maximum allowable flow k_{ij} over edge $i - j$, and a non-negative cost function ‘ a ’ giving the cost ‘ a_{ij} ’ associated with a unit flow over edge $i - j$. A flow ‘ X ’ of value ‘ v ’ is an integral valued function defined on ‘ E ’ satisfying

$$0 \leq x_{ij} \leq k_{ij}, \quad (i, j) \in E \tag{1}$$

$$\sum_{j=1}^n (x_j - x_i) = v \quad ; \quad i=1=0 \quad ; \quad i=2,3,\dots,(n-1) \tag{2}$$

$$= -v \quad ; \quad i=n$$

vertices 1 and n are respectively, called the flow source and sink. Here x_{ij} indicates the amount of allowable flow from i^{th} node to j^{th} node.

The minimal cost flow problem is to find, among all flows X of value v , for which

$$Q(X) = \sum_{(i,j) \in E} x_{ij} a_j = T, \quad \text{Say} \tag{3}$$

is minimum of the associated arcs of the minimum cost flow route and let $Q_1(X), Q_2(X), \dots, Q_k(X)$ are minimum cost routes obtained in ascending order of their values T_1, T_2, \dots, T_k .

Then in the problem of maximum attainable flow in minimum cost in a network, is to find the routes for which the minimum cost flow routes allow maximum possible flow along those routes or,

$$\text{Max flow } F(X) = \min_{x_j \in Q(X)} (x_j \text{ 's}) = v, \tag{4}$$

corresponding to a particular $Q(X)$.

Hence, maximum allowable flow for all permissible minimum cost flow routes is

$$\text{Max flow } F_i(X) = \min_{i=1, \dots, k_p} v_i \tag{5}$$

where k_p stands for permissible minimum cost route. The word ‘permissible’ is in the sense that from among a list of minimum cost routes (in ascending order) k_p is the limit when we are to stop the search corresponding to any of the following situations:

- (i) When there is no link from the source,
- (ii) When there is no link to the destination and
- (iii) When no complete route from the source to the destination exists.

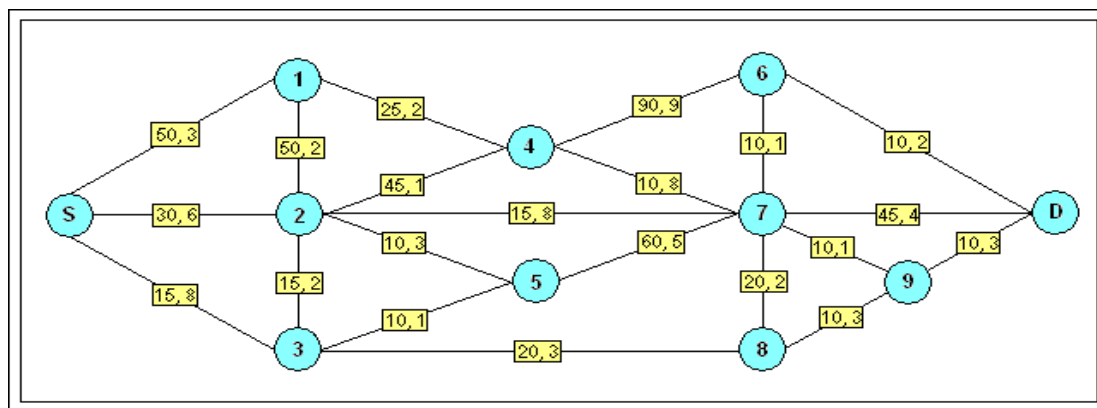
The precedence constraints are satisfied while searching for the minimum cost flow.

Numerical Illustration

The problem is to schedule maximum flow, which costs minimum for a situation given in Fig. 1.

In this graph the first figure in a square on a link indicates its capacity and second figure gives the unit shipping cost. These figures hold for both directions, i.e., the graph under study is an undirected one. Here, the restricted constraints are $(A_2 < A_7), (A_5 < A_7), (A_3 < A_5), (A_3 < A_8), (A_7 < A_9)$ and $(A_1 < A_3)$.

Fig. 1: Given Network



For simplicity, we take $(2 < 7)$, $(5 < 7)$, $(3 < 5)$, $(3 < 8)$, $(7 < 9)$ and $(1 < 3)$.

All these constraints can be simply written as $(2, 5 < 7 < 9)$ and $(1 < 3 < 5, 8)$. The precedence constraints are to be satisfied when the concerned nodes occur in the same route.

Computational Procedure

We solve the problem of finding the Restricted Constraints in the Problem of Maximum Attainable Flow in Minimum Cost in a Network in 4 steps.

In the first step, modify the cost matrix by assigning $d_{ij} = \infty$ for which the tour between node 'i' and node 'j' is not possible following the precedence constraints.

In the second step, using the cost matrix, we construct an alphabet table.

In the third step, we apply the lexicographic search approach to find the valid routes. In the lexicographic search procedure, a computationally simple bound can be obtained as $B(L_k) = V(L_k) + d'(S_k)$ where, $V(L_k)$ is the value of the leader L_k . Evaluation of $d'(S_k)$ are facilitated by alphabet table with nodes $0, 1, 2, \dots, (n-1)$ listed in increasing order of their distances to the home station. The lower bound setting as above helps converging to optimum solution rapidly.

In the fourth step, we select the 1st minimum cost route and search for maximum admissible flow through this route. Delete all those link(s) which are completely busy.

Next we select the 2nd minimum cost and search for maximum admissible flow through this route, deleting all those link(s) which become completely busy in the process.

The process is continued till any one of the following cases arises:

- (i) All the links terminating in destination (D) are full.
- (ii) All the links starting from source (S) are full.
- (iii) Neither the links which leave the source are full nor those which terminate in destination are full but the (S) and (D) do not remain connected.

It may be pointed out that if the given situation enters (i) or (ii) above, we shall terminate the process, as no further

flow will be possible. However, if the situation happens to be in (iii), scheduling of more flow might be possible by diverting the original scheduled flow due to the fact that links starting from source have more capacity for outflow and links terminating in destination can allow more inflow. It may be noted that any diversion will require more cost of shipping even for those items which are originally scheduled to be at a lesser cost of shipping.

Also, care has to be taken throughout the process that if alternative routes (in the sense of shipping cost) between any two nodes are available, the choice will be for a path whose capacity is more, or if possible, engage all such alternative routes.

The detailed algorithm and flow chart of the problem are described in next section.

Part-I

Formation of Cost Matrix and Alphabet Table(s)

Step1: Modify the cost matrix by assigning $d_{ij} = \infty$ for which the tour between node 'i' and node 'j' is not possible following the precedence constraints.

Step2: Using modified cost matrix, list under column i , ($i = 0, 1, 2, \dots, (n-1)$) having links from column i with the nodes $\{0, 1, 2, \dots, (n-1)\}$ in order $J_0^{(i)}, J_1^{(i)}, \dots, J_{n-1}^{(i)}$ such that the cost values are in ascending order of that column. The ordering $(J_0, J_1, \dots, J_{n-1})$ so obtained for a given node j , is defined as the alphabetic order for column j and the table thus formed containing all the columns, is called the alphabet table (Table 4). In alphabet table along the ascending cost value the respective link position value is also accommodated for each column.

Step 3: Construct another table using the last column of the cost matrix, arranging the nodes $J_i^{(i)}$, such that $r < s$ if $d_{rD} \leq d_{sD}$, the ordering thus obtained is alphabet table (cf. Table 4). This arrangement of column matrix is used for lower bound setting. The alphabet table (cf. Table 4) thus enables us to list the tours in a systematic way such that the values of 'incomplete words' (leaders) at different stages also present a useful hierarchical structure. We can set 'lower bounds' to this incomplete word for quick convergence to the optimal solution.

Setting up of Lower Bound

A computationally simple bound can be obtained as $B(L_k) = V(L_k) + d'(S_k)$ where, $V(L_k)$ is the value of the leader L_k . Evaluation of $d'(S_k)$ are facilitated by alphabet table (cf. Table 4) with nodes $0, 1, 2, \dots, (n-1)$ listed in increasing order of their distances to D , the destination.

Suppose at some stage k , the leader of order k is $L_k = \{a_0, a_1, a_2, \dots, a_k\}$ and $S_k = \{a_0, a_1, a_2, \dots, a_k; D\}$, the corresponding node set.

Since the flow has to reach to D , we can examine at stage k , at least how much the flow would take to go to D from any of the unvisited stations, i.e.,

$$d'(S_k) = \min_{j \in S_k} d(j, D) \quad (6)$$

If we have a trial solution L^* of value V_t and if $V_t < B(L_k)$, it is obvious that L_k can not contain any complete tour which is even as good as the solution L^* at hand and we jump over the block and search in the next entry of order $k-1$. On the other hand,

If $B(L_k) < V_t$, it may give a better solution than at hand and so we proceed to complete the route and go to next block and examine the possibility of a better solution. If $B(L_k) = V_t$ on completion we might get an alternate solution of value V_t . If $B(L_k) > V_t$, we reject the current leader and go back to $(k-1)^{\text{th}}$ step and examine the next entry of that stage and so on.

Part-II

Lexicographic Search

We start with a trial solution V_t with a sequence T .

Step 1: Let a be the

corresponding flow sequence of L_k .

with $k=1$.

The first entry of the block 1, go to step 2.

Step 2: Is $k \leq n$? If yes go to 3. If no go to 5c.

Step 3: Compute the cost from .

with. Go to 4.

Step 4: Is If yes goto 6. If no goto 5.

Step 5: Is (sink node)? If yes goto 8. If no goto 5a.

Step 5a: Is the elements in the respective column of is exhausted?

If yes goto 5c. If no goto 5b.

Step 5b : where, is the first sub-block of .

Put $k=k+1$, goto 2.

Step 5c: Is $k=1$? If yes goto 7. If no goto 6.

Step 6: Move out of the present L_k and goto next block of order $k-1$, select the next variable entry. Goto 2.

Step 6a: Check for fulfillment of restricted constraints

Is If yes, go to 7. If no go to 6.

Step 7: Is the list of column 1 exhausted?

If yes goto 12. If no goto 11.

Step 8: Compute the flow from.

(say), Goto 9.

Step 9: Is If yes goto 9a. If no goto 10.

Step 9a: Block the corresponding arc. Goto 6.

Step 10: and . Goto 10a.

Step 10a: Set $k=k-1$. Goto 2.

Step 11: Take the next available entry in L_k . Goto 1.

Step 12: Search is over; current T gives minimum cost maximum flow (MCMF)

in a single channel with a value V_t . Goto 13.

Step 13: Record final value and . Goto 14.

Step 14: $i=1, 2, \dots, k$. Goto 14a.

Step 14a: Reconstruct the revised alphabet table with the latest available arcs. goto 15.

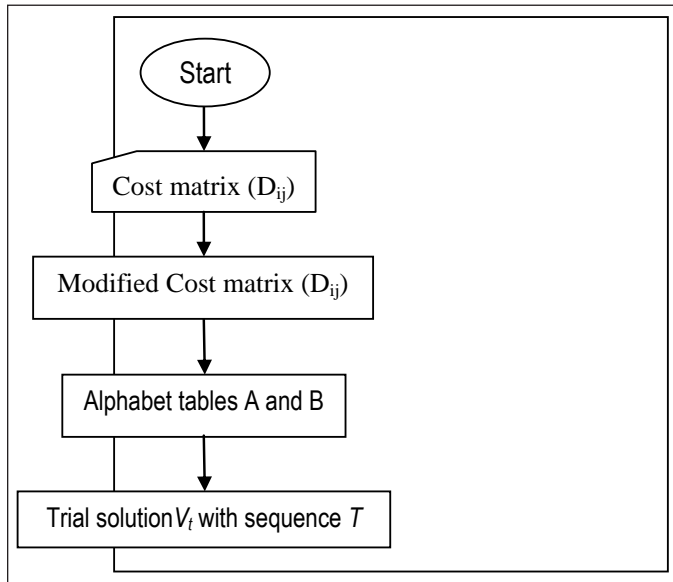
Step 15: Repeat the algorithm until the flow is zero from a source node to sink node. Goto 16.

Step 16: Cumulate the cost obtained from and flow obtained from for all the different sequences. Goto 17.

Step 17: Stop and end.

Flow charts of the solution procedure have been given in Fig. 2. and Fig.3.

Fig. 2: Part I: Formation of Alphabet Table and a Trial Solution



Solution

To apply the lexicographic search approach for obtaining the optimum solution of minimum cost and maximum flow problem first we construct a cost (distance) and flow (capacity) matrix with the help of the given network (Fig.1). The matrix is in symmetric nature when the network is an undirected one, otherwise it is asymmetric. The set of nodes are taken as row and column indices. The cost and flow associated with a pair of nodes is represented in the respective position of the cost matrix. If there is no direct link between a pair of nodes then the corresponding cost will be taken as infinity in the case cost minimisation problems. Conveniently, the bold numbers in a cell of Table 2 indicates the unit shipping cost of the respective flow. The cost-flow matrix is shown in Table 2.

Here the restricted and unrestricted stations are:

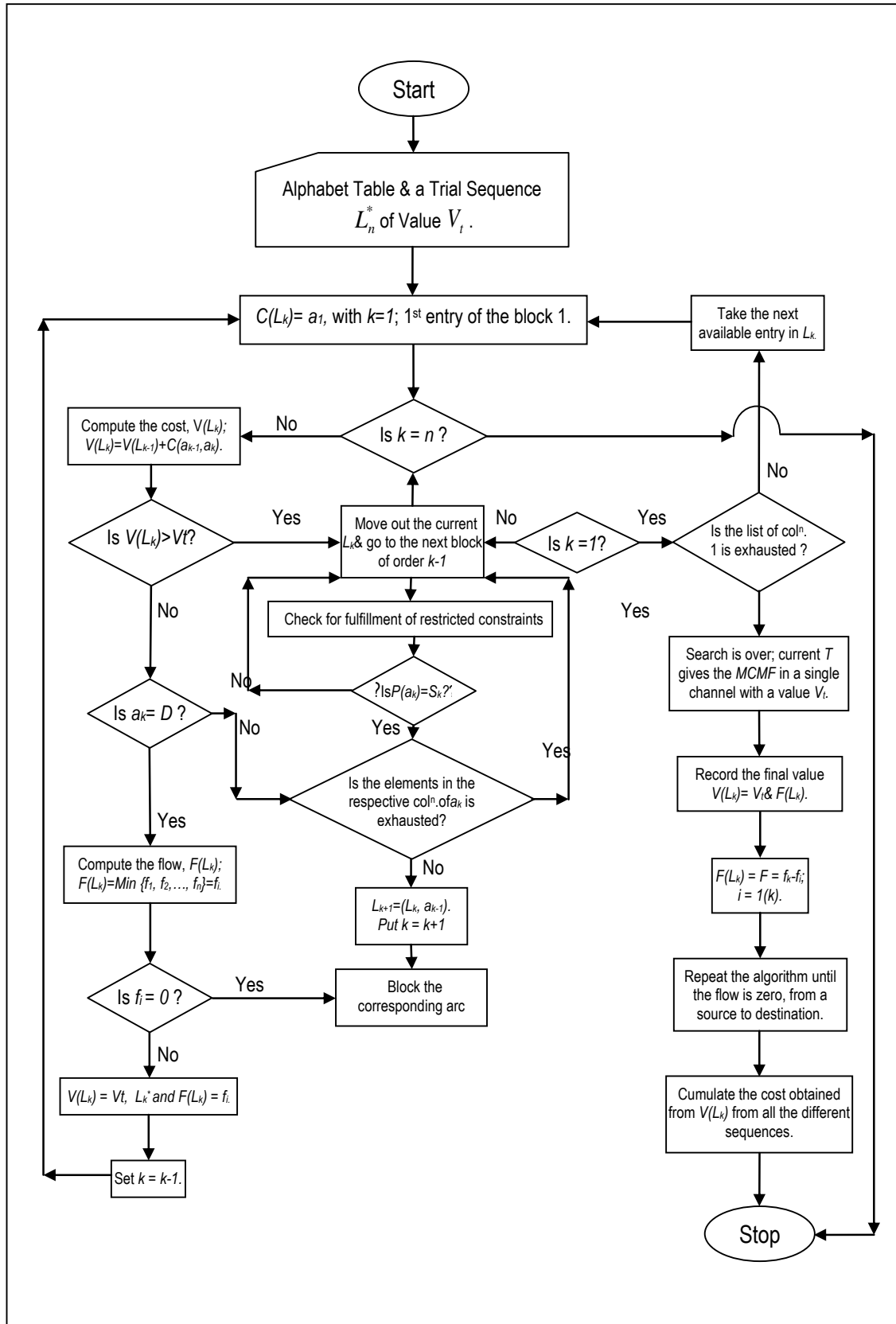
Restricted stations:	1, 2, 3, 5, 7, 8, 9
Un-restricted stations:	4, 6

All the given precedence constraints can be simply written as (2, 5 < 7 < 9) and (1 < 3 < 5, 8) and these constraints lead to the following implications:

Table 2: Cost-Flow Matrix

Stations	S	1	2	3	4	5	6	7	8	9	D
S	-	3 ⁰	6 ⁰	8 ⁵	↔	↔	↔	↔	↔	↔	↔
1	3 ⁰	-	2 ⁰	↔	2 ³	↔	↔	↔	↔	↔	↔
2	6 ⁰	2 ⁰	-	2 ⁵	1 ⁵	3 ⁰	↔	8 ⁵	↔	↔	↔
3	8 ⁵	↔	2 ⁵	-	↔	1 ⁰	↔	↔	3 ⁰	↔	↔
4	↔	2 ³	1 ⁵	↔	-	↔	9 ⁰	8 ⁰	↔	↔	↔
5	↔	↔	3 ⁰	1 ⁰	↔	-	↔	5 ⁰	↔	↔	↔
6	↔	↔	↔	↔	9 ⁰	↔	-	1 ⁰	↔	↔	2 ⁰
7	↔	↔	8 ⁵	↔	8 ⁰	5 ⁰	1 ⁰	-	2 ⁰	1 ⁰	4 ⁵
8	↔	↔	↔	3 ⁰	↔	↔	↔	2 ⁰	-	3 ⁰	↔
9	↔	↔	↔	↔	↔	↔	↔	1 ⁰	3 ⁰	-	3 ⁰
D	↔	↔	↔	↔	↔	↔	2 ⁰	4 ⁵	↔	3 ⁰	-

Fig. 3: Part II: Lexicographic Search



1→5=∞	2→9=∞	3→1=∞	5→1=∞	7→2=∞	8→1=∞	9→2=∞
1→8=∞			5→3=∞	7→5=∞	8→3=∞	9→5=∞
			5→9=∞			9→7=∞

The links not existing due to the structure of the problem are:

9→2=∞, 9→5=∞, 3→1=∞, 5→1=∞ and 8→1=∞.

Hence the reduced distance matrix is

table are the cost values in ascending order with its connected link from the respective column of cost-flow matrix. The flow is moving from source to sink, so that the connections 1- S, 2- S and 3- S are neglected. The first number indicates the link from the respective node; the second number indicates the cost on the same link.

Finding the First Minimum Cost Route(s)

Searching Mechanism for the Optimal Solution

Construction of the Alphabet Table

The systematic version of the lexicographic search method is presented here to find the optimum solution of the problem (Fig.1). The search mechanism is basing on the alphabet table i.e. it starts from source point and moves

The alphabet table (Table 4) is obtained from the cost-flow matrix. The entries in each column of the alphabet

Table 3: Modified Cost Matrix

Stations	S	1	2	3	4	5	6	7	8	9	D
S	-	3 ⁰	6 ⁰	8 ⁵	↔	↔	↔	↔	↔	↔	↔
1	3 ⁰	-	2 ⁰	↔	2 ³	↔	↔	↔	↔	↔	↔
2	6 ⁰	2 ⁰	-	2 ⁵	1 ⁴	3 ⁰	↔	8 ⁵	↔	↔	↔
3	8 ⁵	↔	2 ⁵	-	↔	1 ⁰	↔	↔	3 ⁰	↔	↔
4	↔	2 ³	1 ⁴	↔	-	↔	9 ⁹	8 ⁰	↔	↔	↔
5	↔	↔	3 ⁰	∞ ⁰	↔	-	↔	5 ⁶	↔	↔	↔
6	↔	↔	↔	↔	9 ⁹	↔	-	1 ⁰	↔	↔	2 ⁰
7	↔	↔	∞ ⁵	↔	8 ⁰	∞ ⁶	1 ⁰	-	2 ⁰	1 ⁰	4 ⁴
8	↔	↔	↔	∞ ⁰	↔	↔	↔	2 ⁰	-	3 ⁰	↔
9	↔	↔	↔	↔	↔	↔	↔	∞ ⁰	3 ⁰	-	3 ⁰
D	↔	↔	↔	↔	↔	↔	2 ⁰	4 ⁴	↔	3 ⁰	-

Table 4: Alphabet Table

S↓	1	2	3	4	5	6	7	8	9	For LB→D
1-3	2-2	4-1	5-1	2-1	2-3	7-1	6-1	7-2	8-3	6-2
2-6	4-2	1-2	2-2	1-2	7-5	D-2	9-1	9-3	D-3	9-3
3-8		3-2	8-3	7-8	3-∞	4-9	8-2	3-∞	7-∞	7-4
		5-3		6-9			D-4			
		7-8					4-8			
							2-∞			
							5-∞			

Table 5: Lexicographic Search Table (Partial) from Table 4

Route No.	S↓										Cost
1	$1_{(3)}3$	$2_{(5)}2$	$4_{(6)}1$	$7_{(4)}8$	$6_{(5)}1$	$D_{(7)}2$					$\mathbb{T} = V_t$
						×					
2						$D_{(8)}4$					$> V_t$
						×					
3					$6_{(5)+2}9$	$7_{(6)+2}1$					$> V_t$
4						$D_{(7)}2$					17
						×					
					×						
5			$3_{(7)+2}2$	$5_{(8)+2}1$	$7_{(8)+2}5$	$6_{(4)+2}1$	$D_{(6)}2$				$\mathbb{6} = V_t$
6							$4_{(3)}9$				$> V_t$
							×				
7							$9_{(4)+2}1$	$8_{(7)}3$			$> V_t$
							×				
8							$8_{(5)+2}2$	$9_{(8)+2}3$			$> V_t$
							×				
9						$D_{(7)}4$				$> V_t$	
						×					
						×					
10				$8_{(0)+2}3$	$7_{(2)+2}2$	$6_{(8)+2}1$	$D_{(5)}2$			$\mathbb{5} = V_t$	
						×					
11						$9_{(3)+2}1$				$> V_t$	
12						$D_{(6)}4$				$> V_t$	
						×					
13						$9_{(3)+2}3$	$D_{(6)}3$			$> V_t$	
						×					
						×					
14			$5_{(8)+2}3$	$7_{(8)+2}5$	$9_{(4)+2}1$					$> V_t$	
					$D_{(7)}4$					$> V_t$	
					×						
					×						
15			$7_{(8)+2}8$							$> V_t$	

Fig. 5: First Modified Residual Network

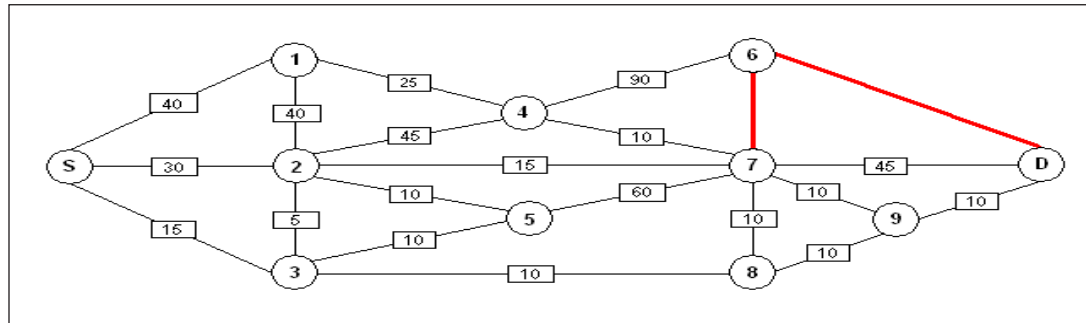
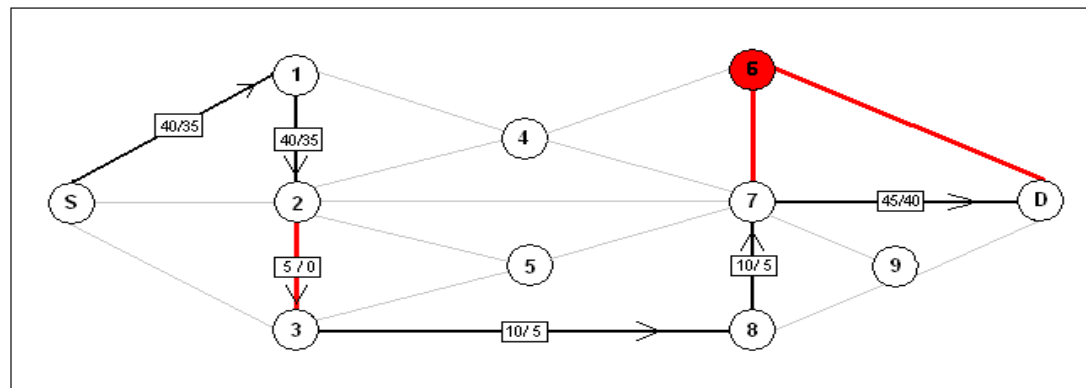


Table 7: 1st Modified Alphabet Table

S↓	1	2	3	4	5	7	8	9	For LB →D
Predecessor♦	(1 < 3)	(2 < 7)	(3 < 5,8)		(5 < 7)	(7 < 9)			
1-3	2-2	4-1	5-1	2-1	2-3	9-1	7-2	8-3	9-3
2-6	4-2	1-2	2-2	1-2	7-5	8-2	9-3	D-3	7-4
3-8		3-2	8-3	7-8		D-4			
		5-3				4-8			
		7-8							

Fig. 6: Network Showing the Route of Cost 16 and Flow 5



next reduced alphabet table. The first revised one can be observed in Table 7.

The search is complete.

The available routes of 2nd minimum cost 16 and are shown in Table 9:

Since all the routes have the same maximum flow (i.e., 5) and using $(2) \cap (3)$ with capacity 5, only one route is possible, therefore, we can take any one route from this stage, say, the route (10) and the network diagram of the maximum flow 5 with minimum cost 16 is shown in Fig.6.

Since the link $(2) \diamond (3)$ is completely busy from Fig.4 and we cannot pass any further flow through this link, therefore, the two other valid routes (9) and (11) are being neglected. Because of the same reason routes (6) and (8) with minimum cost 17 are not usable. The remaining available capacities are shown in the network diagram of Fig.7.

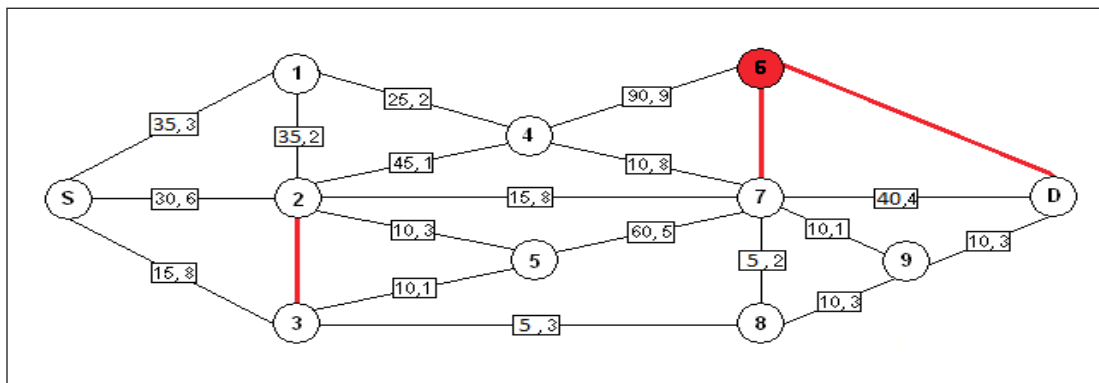
Finding the Third Minimum Cost Route(s)

Since the link $(2) \cap (3)$ is completely busy and we

Table 9: Valid Routes having Minimum Cost 16

Route No.	Valid routes having minimum cost 16	Max. Flow
9	$(S) \overset{0}{\underset{3}{\blacklozenge}} (1) \overset{0}{\underset{2}{\blacklozenge}} (2) \overset{5}{\underset{2}{\blacklozenge}} (3) \overset{0}{\underset{3}{\blacklozenge}} (8) \overset{0}{\underset{2}{\blacklozenge}} (7) \overset{0}{\underset{1}{\blacklozenge}} (9) \overset{0}{\underset{3}{\blacklozenge}} (D)$	5
10	$(S) \overset{0}{\underset{3}{\blacklozenge}} (1) \overset{0}{\underset{2}{\blacklozenge}} (2) \overset{5}{\underset{2}{\blacklozenge}} (3) \overset{0}{\underset{3}{\blacklozenge}} (8) \overset{0}{\underset{2}{\blacklozenge}} (7) \overset{5}{\underset{4}{\blacklozenge}} (D)$	5
11	$(S) \overset{0}{\underset{3}{\blacklozenge}} (1) \overset{0}{\underset{2}{\blacklozenge}} (2) \overset{5}{\underset{2}{\blacklozenge}} (3) \overset{0}{\underset{3}{\blacklozenge}} (8) \overset{0}{\underset{3}{\blacklozenge}} (9) \overset{0}{\underset{3}{\blacklozenge}} (D)$	5

Fig. 7: Second Modified Residual Network



cannot pass any further flow from this link, therefore, we delete the link $(2) \cap (3)$ from the preceding alphabet table and revised alphabet table is shown in Table 10.

The search is completed.

The available valid routes of cost 17 with the different the

maximum flows for the same are shown in Table 12.

Since, with minimum cost 17, the maximum flow is 15 and is available in the route number (11), therefore we first include the route number (11) in our solution and $(2) \cap (7)$ become full, we reject route (10). Similarly, we select arbitrarily from among routes with capacity

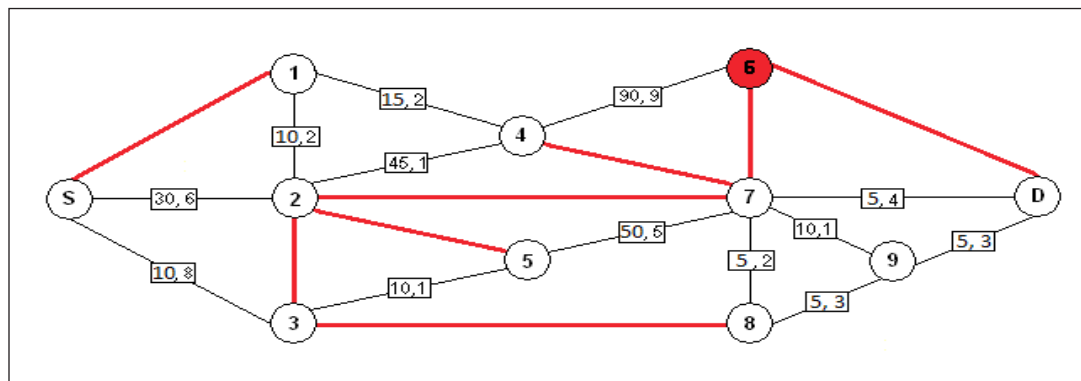
Table 10: 2nd Modified Alphabet Table

S↓	1	2	3	4	5	7	8	9	For LB →D
Predecessor→	(1 < 3)	(2 < 7)	(3 < 5,8)		(5 < 7)	(7 < 9)			
1-3	2-2	4-1	5-1	2-1	2-3	9-1	7-2	8-3	9-3
2-6	4-2	1-2	8-3	1-2	7-5	8-2	9-3	D-3	7-4
3-8		5-3		7-8		D-4			
		7-8				4-8			

Table 12: Valid Route having Minimum Cost 17

Route No.	Valid route having minimum cost 17	Max. flow
6	$(S) \begin{smallmatrix} 3 \\ \blacklozenge \\ 3 \end{smallmatrix} (1) \begin{smallmatrix} 3 \\ \blacklozenge \\ 2 \end{smallmatrix} (2) \begin{smallmatrix} 0 \\ \blacklozenge \\ 3 \end{smallmatrix} (5) \begin{smallmatrix} 0 \\ \blacklozenge \\ 5 \end{smallmatrix} (7) \begin{smallmatrix} 0 \\ \blacklozenge \\ 1 \end{smallmatrix} (9) \begin{smallmatrix} 0 \\ \blacklozenge \\ 3 \end{smallmatrix} (D)$	5
8	$(S) \begin{smallmatrix} 3 \\ \blacklozenge \\ 3 \end{smallmatrix} (1) \begin{smallmatrix} 3 \\ \blacklozenge \\ 2 \end{smallmatrix} (2) \begin{smallmatrix} 0 \\ \blacklozenge \\ 3 \end{smallmatrix} (5) \begin{smallmatrix} 0 \\ \blacklozenge \\ 5 \end{smallmatrix} (7) \begin{smallmatrix} 0 \\ \blacklozenge \\ 4 \end{smallmatrix} (D)$	10
10	$(S) \begin{smallmatrix} 3 \\ \blacklozenge \\ 3 \end{smallmatrix} (1) \begin{smallmatrix} 3 \\ \blacklozenge \\ 2 \end{smallmatrix} (2) \begin{smallmatrix} 5 \\ \blacklozenge \\ 8 \end{smallmatrix} (7) \begin{smallmatrix} 0 \\ \blacklozenge \\ 1 \end{smallmatrix} (9) \begin{smallmatrix} 0 \\ \blacklozenge \\ 3 \end{smallmatrix} (D)$	10
11	$(S) \begin{smallmatrix} 3 \\ \blacklozenge \\ 3 \end{smallmatrix} (1) \begin{smallmatrix} 3 \\ \blacklozenge \\ 2 \end{smallmatrix} (2) \begin{smallmatrix} 5 \\ \blacklozenge \\ 8 \end{smallmatrix} (7) \begin{smallmatrix} 0 \\ \blacklozenge \\ 4 \end{smallmatrix} (D)$	15
17	$(S) \begin{smallmatrix} 3 \\ \blacklozenge \\ 3 \end{smallmatrix} (1) \begin{smallmatrix} 3 \\ \blacklozenge \\ 2 \end{smallmatrix} (4) \begin{smallmatrix} 0 \\ \blacklozenge \\ 8 \end{smallmatrix} (7) \begin{smallmatrix} 0 \\ \blacklozenge \\ 1 \end{smallmatrix} (9) \begin{smallmatrix} 0 \\ \blacklozenge \\ 3 \end{smallmatrix} (D)$	10
18	$(S) \begin{smallmatrix} 3 \\ \blacklozenge \\ 3 \end{smallmatrix} (1) \begin{smallmatrix} 3 \\ \blacklozenge \\ 2 \end{smallmatrix} (4) \begin{smallmatrix} 0 \\ \blacklozenge \\ 8 \end{smallmatrix} (7) \begin{smallmatrix} 0 \\ \blacklozenge \\ 4 \end{smallmatrix} (D)$	10
27	$(S) \begin{smallmatrix} 5 \\ \blacklozenge \\ 8 \end{smallmatrix} (3) \begin{smallmatrix} 5 \\ \blacklozenge \\ 3 \end{smallmatrix} (8) \begin{smallmatrix} 5 \\ \blacklozenge \\ 2 \end{smallmatrix} (7) \begin{smallmatrix} 0 \\ \blacklozenge \\ 1 \end{smallmatrix} (9) \begin{smallmatrix} 0 \\ \blacklozenge \\ 3 \end{smallmatrix} (D)$	5
28	$(S) \begin{smallmatrix} 5 \\ \blacklozenge \\ 8 \end{smallmatrix} (3) \begin{smallmatrix} 5 \\ \blacklozenge \\ 3 \end{smallmatrix} (8) \begin{smallmatrix} 5 \\ \blacklozenge \\ 2 \end{smallmatrix} (7) \begin{smallmatrix} 0 \\ \blacklozenge \\ 4 \end{smallmatrix} (D)$	5
29	$(S) \begin{smallmatrix} 5 \\ \blacklozenge \\ 8 \end{smallmatrix} (3) \begin{smallmatrix} 5 \\ \blacklozenge \\ 3 \end{smallmatrix} (8) \begin{smallmatrix} 0 \\ \blacklozenge \\ 3 \end{smallmatrix} (9) \begin{smallmatrix} 0 \\ \blacklozenge \\ 3 \end{smallmatrix} (D)$	5

Fig. 8: Third Modified Residual Network



10, the route (8) and since $(2) \cap (5)$ becomes full we reject route (6). Similarly we select route (18) and reject route (17). Lastly, we select route (28) and it rejects route numbers (27) and (29). We get the resulting flow network as in Fig. 8.

In this step link $(3) \cap (8)$ is completely busy. Neglecting the routes having the busylinks $(S) \blacklozenge (1), (2) \cap (3), (2) \cap (5), (2) \cap (7), (3) \cap (8), (4) \cap (7), (6) \blacklozenge (D)$

& $(7) \cap (6)$, then no other valid routes of cost 17 are available.

Finding the Fourth Minimum Cost Route(s)

Neglect all the busy routes of cost 17 from the previous network. The further modified alphabet table is shown in Table 13.

Table 13: 3rd Modified Alphabet Table

$S \downarrow$ Predecessor \rightarrow	1	2	3	4	5	7	8	9	For LB $\rightarrow D$
	(1 < 3)	(2 < 7)	(3 < 5,8)		(5 < 7)	(7 < 9)			
2-6	2-2	4-1	5-1	2-1	2-3	9-1	7-2	8-3	9-3
3-8	4-2	1-2		1-2	7-5	8-2	9-3	D-3	7-4
						D-4			
						4-8			

Table 14: Lexicographic Search Table from Table 13

Route No.	$S \downarrow$									Cost
1		$4 \xrightarrow{(7)} 1$								NF
2	$2 \xrightarrow{(6)} 6$	$1 \xrightarrow{(8)} 2$								NF
		x								
3			$2 \xrightarrow{(2)} 3$	$4 \xrightarrow{(8)} 1$						NF
			x							
4					$8 \xrightarrow{(8)} 3$					NF
5				$9 \xrightarrow{(5)} 1$	$D \xrightarrow{(8)} 3$					$\mathbb{8} = V_t$
				x						
6	$3 \xrightarrow{(8)} 8$	$5 \xrightarrow{(9)} 1$	$7 \xrightarrow{(4)} 5$		$8 \xrightarrow{(8)+3} 3$					$> V_t$
7					$D \xrightarrow{(8)} 4$					18
					x					
		x								
	x									

Table 15: Valid Routes having Minimum Cost 18

Route No.	Valid routes having minimum cost 18	Max. Flow
5	$(S) \xrightarrow{0} \diamond_8 (3) \xrightarrow{0} \diamond_1 (5) \xrightarrow{6} \diamond_5 (7) \xrightarrow{0} \diamond_1 (9) \xrightarrow{5} \diamond_3 (D)$	5
7	$(S) \xrightarrow{0} \diamond_8 (3) \xrightarrow{0} \diamond_1 (5) \xrightarrow{6} \diamond_5 (7) \xrightarrow{5} \diamond_4 (D)$	5

The search is complete.

In Table 15, the maximum flow is 5 (with minimum cost 18) is available in the route number (5) and (7). Therefore, we can take any one of them; say (5) first, and then we check whether route (7) is possible along with route (5).

The allowable flow up to the 7th node is 10 in the specified routes. Now the flow can send from (7) \diamond (D) directly and also via the 9th node. So that both the routes can be combined then we get flows of value 5+5=10 and the resulting network is given in Fig.9.

Fig. 9: Fourth Modified Residual Network

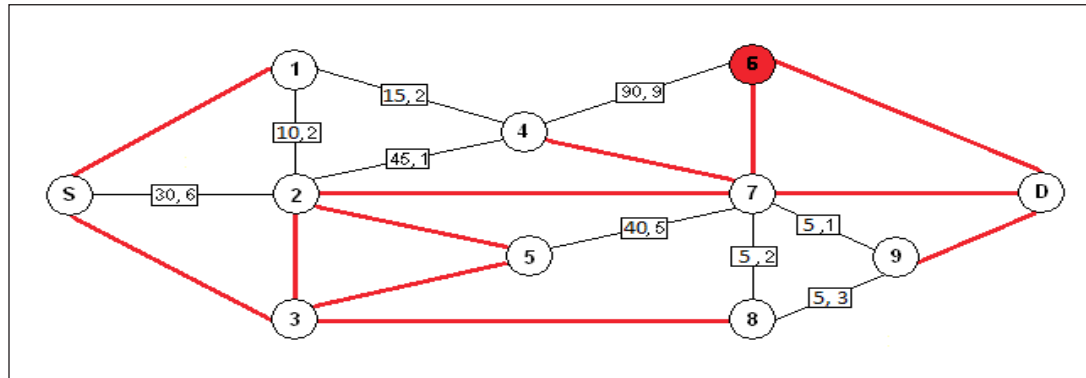


Table 16: Routes in the Optimum Solution

LS Table no.	Route no.	Routes in the optimum solution	Min cost	Max flow
5	10	$(S) \begin{smallmatrix} 6 \\ \blacklozenge \\ 3 \end{smallmatrix} (1) \begin{smallmatrix} 6 \\ \blacklozenge \\ 2 \end{smallmatrix} (2) \begin{smallmatrix} 5 \\ \blacklozenge \\ 2 \end{smallmatrix} (3) \begin{smallmatrix} 0 \\ \blacklozenge \\ 3 \end{smallmatrix} (8) \begin{smallmatrix} 0 \\ \blacklozenge \\ 2 \end{smallmatrix} (7) \begin{smallmatrix} 0 \\ \blacklozenge \\ 1 \end{smallmatrix} (6) \begin{smallmatrix} 0 \\ \blacklozenge \\ 2 \end{smallmatrix} (D)$	15	10
8	10	$(S) \begin{smallmatrix} 0 \\ \blacklozenge \\ 3 \end{smallmatrix} (1) \begin{smallmatrix} 0 \\ \blacklozenge \\ 2 \end{smallmatrix} (2) \begin{smallmatrix} 5 \\ \blacklozenge \\ 2 \end{smallmatrix} (3) \begin{smallmatrix} 0 \\ \blacklozenge \\ 3 \end{smallmatrix} (8) \begin{smallmatrix} 0 \\ \blacklozenge \\ 2 \end{smallmatrix} (7) \begin{smallmatrix} 5 \\ \blacklozenge \\ 4 \end{smallmatrix} (D)$	16	5
11	11	$(S) \begin{smallmatrix} 5 \\ \blacklozenge \\ 3 \end{smallmatrix} (1) \begin{smallmatrix} 5 \\ \blacklozenge \\ 2 \end{smallmatrix} (2) \begin{smallmatrix} 5 \\ \blacklozenge \\ 8 \end{smallmatrix} (7) \begin{smallmatrix} 0 \\ \blacklozenge \\ 4 \end{smallmatrix} (D)$	17	10
	8	$(S) \begin{smallmatrix} 5 \\ \blacklozenge \\ 3 \end{smallmatrix} (1) \begin{smallmatrix} 5 \\ \blacklozenge \\ 2 \end{smallmatrix} (2) \begin{smallmatrix} 0 \\ \blacklozenge \\ 3 \end{smallmatrix} (5) \begin{smallmatrix} 0 \\ \blacklozenge \\ 5 \end{smallmatrix} (7) \begin{smallmatrix} 0 \\ \blacklozenge \\ 4 \end{smallmatrix} (D)$	17	15
	27	$(S) \begin{smallmatrix} 5 \\ \blacklozenge \\ 3 \end{smallmatrix} (1) \begin{smallmatrix} 5 \\ \blacklozenge \\ 2 \end{smallmatrix} (4) \begin{smallmatrix} 0 \\ \blacklozenge \\ 8 \end{smallmatrix} (7) \begin{smallmatrix} 0 \\ \blacklozenge \\ 4 \end{smallmatrix} (D)$	17	10
	29	$(S) \begin{smallmatrix} 5 \\ \blacklozenge \\ 8 \end{smallmatrix} (3) \begin{smallmatrix} 5 \\ \blacklozenge \\ 3 \end{smallmatrix} (8) \begin{smallmatrix} 0 \\ \blacklozenge \\ 3 \end{smallmatrix} (9) \begin{smallmatrix} 0 \\ \blacklozenge \\ 3 \end{smallmatrix} (D)$	17	5
14	5	$(S) \begin{smallmatrix} 0 \\ \blacklozenge \\ 8 \end{smallmatrix} (3) \begin{smallmatrix} 0 \\ \blacklozenge \\ 1 \end{smallmatrix} (5) \begin{smallmatrix} 6 \\ \blacklozenge \\ 5 \end{smallmatrix} (7) \begin{smallmatrix} 0 \\ \blacklozenge \\ 1 \end{smallmatrix} (9) \begin{smallmatrix} 5 \\ \blacklozenge \\ 3 \end{smallmatrix} (D)$	18	5
	7	$(S) \begin{smallmatrix} 0 \\ \blacklozenge \\ 8 \end{smallmatrix} (3) \begin{smallmatrix} 0 \\ \blacklozenge \\ 1 \end{smallmatrix} (5) \begin{smallmatrix} 6 \\ \blacklozenge \\ 5 \end{smallmatrix} (7) \begin{smallmatrix} 5 \\ \blacklozenge \\ 4 \end{smallmatrix} (D)$	18	5
Total			135	65

It is now observed from Fig.9 that all the direct links terminating in destination (D) becomes full, and no further flow will be possible. Therefore, the further search is stopped and we reached at optimum solution. The optimum solution is given in Table 16.

Therefore, the maximum possible flow will be 65 with minimum cost 135 units.

Computational Experience

A computer program of the algorithm has been developed

in C language and is tested on the system HP COMPAQ dx2280 and Intel Pentium D Processors. Random numbers are used to construct the cost matrix. Table 17 gives the list of the problems tried along with the average CPU run time (in seconds) for solving them.

Conclusion

It is seen that the time required for the search of the optimal solution is fairly less.

Table 17: CPU Run Time (in Sec.)

Serial number	Number of stations	No. of problems tried in the respective dimensions	Average CPU runs time(in Sec.)	
			Alphabet table	Search table
1	5	6	0.00000	0.0000
2	8	6	0.00000	0.0000
3	10	6	0.05494	0.0000
4	12	6	0.05494	0.0349
5	15	6	0.08932	0.5812
6	18	6	0.08932	1.3841
8	20	6	0.10989	1.9794
9	25	6	0.10989	2.2649
10	30	6	0.16483	3.0366
11	40	6	0.85389	3.4738
12	50	6	1.54920	4.8643

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